

Recap:

Discussed dynamics of Newtonian fluids

Described by conservation laws
for ρ , $\rho \vec{v}$, $\epsilon + \frac{1}{2} \rho \vec{v}^2$

$$\frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot \vec{J}_\rho = 0$$

$$\frac{\partial (\rho \vec{v})}{\partial t} + \vec{\nabla} \cdot \vec{J}_p = 0$$

$$\frac{\partial (\epsilon + \frac{1}{2} \rho \vec{v}^2)}{\partial t} + \vec{\nabla} \cdot \vec{J}_E = 0$$

closed by constitutive relations
for fluxes

$$\vec{J}_\rho = \rho \vec{v} \quad (\text{no non-equilibrium corrections
due to definition of } \vec{v})$$

$$\vec{J}_p^{AB} = \Pi^{AB} + \rho v^A v^B$$

stress tensor

$$\underline{\underline{\Pi}} = \left(p - \rho (\vec{\nabla} \cdot \vec{v}) \right) \underline{\underline{1}} - 2\eta \underline{\underline{\Theta}}$$

$$\text{with } \Theta^{AB} = \frac{1}{2} \left(\frac{\partial v^A}{\partial x^B} + \frac{\partial v^B}{\partial x^A} \right) - \frac{1}{3} (\vec{\nabla} \cdot \vec{v}) \delta^{AB}$$

$$\vec{J}_E = \left(\epsilon + \frac{1}{2} \rho \vec{v}^2 \right) \vec{v} + \underline{\underline{\Pi}} \vec{v} - \kappa \vec{\nabla} T$$

We found

$$\frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot (\rho \vec{v}) = 0 \quad \text{continuity equation}$$

and assuming ρ, η to be constant

$$\rho \left[\frac{\partial \vec{v}}{\partial t} + (\vec{v} \cdot \vec{\nabla}) \vec{v} \right] = -\vec{\nabla} P + \rho \vec{\nabla} \cdot (\vec{\tau} \cdot \vec{v}) + \eta \left(\Delta \vec{v} + \frac{1}{3} \vec{\nabla} (\vec{\nabla} \cdot \vec{v}) \right)$$

Navier-Stokes equation

con servative + friction forces

In particular for an incompressible fluid

$$\rho = \text{const}$$

$$\Rightarrow \boxed{\vec{\nabla} \cdot \vec{v} = 0}$$

cont eqn

$$\rho \left[\frac{\partial \vec{v}}{\partial t} + (\vec{v} \cdot \vec{\nabla}) \vec{v} \right] = -\vec{\nabla} P + \eta \Delta \vec{v}$$

Similarly we can write down the energy balance equation

$$\frac{d}{dt} \left(\epsilon + \frac{1}{2} \rho \vec{v}^2 \right) + \vec{\nabla} \cdot \vec{J}_E = 0$$

$$\vec{J}_E = \left(\epsilon + \frac{1}{2} \rho \vec{v}^2 \right) \vec{v} + \underline{\underline{\Pi}} \vec{v} + \vec{J}_q$$

with $\underline{\underline{\Pi}} = \left(P - \rho (\vec{\nabla} \cdot \vec{v}) \right) \underline{\underline{1}} - 2\eta \underline{\underline{\sigma}}$

$$\vec{J}_q = -\kappa \vec{\nabla} T$$

So using

$$\begin{aligned} 2\eta \sigma^{aB} v^B &= \left[\eta \left(\frac{\partial v^k}{\partial x^B} + \frac{\partial v^B}{\partial x^k} \right) - \frac{2}{3} \eta (\vec{\nabla} \cdot \vec{v}) \delta^{aB} \right] v^B \\ &= \eta (\vec{\nabla} \cdot \vec{v}) v^a + \eta \vec{\nabla} \cdot \left(\frac{1}{2} \vec{v}^2 \right) - \frac{2}{3} \eta (\vec{\nabla} \cdot \vec{v}) v^a \end{aligned}$$

we get

$$\begin{aligned} \frac{d}{dt} \left(\epsilon + \frac{1}{2} \rho \vec{v}^2 \right) + \vec{\nabla} \cdot \left[\left(\epsilon + \rho + \frac{1}{2} \rho \vec{v}^2 \right) \vec{v} \right. \\ \left. - \eta \left((\vec{\nabla} \cdot \vec{v}) \vec{v} + \vec{\nabla} \cdot \left(\frac{1}{2} \vec{v}^2 \right) - \frac{2}{3} \vec{v} (\vec{\nabla} \cdot \vec{v}) \right) \right. \\ \left. - \rho \vec{v} (\vec{\nabla} \cdot \vec{v}) - \kappa \vec{\nabla} T \right] = 0 \end{aligned}$$

Entropy production in NS eqn

Since entropy is frame independent
 can look at entropy production in
 LRF which simplifies the calculations

~~$$\Theta_S = \sum_i \mathbb{J}_i \cdot \mathbb{F}_i$$~~

$$\Theta_S = \sum_i (\mathbb{J}_i - \mathbb{J}_i^{eq}) \cdot \mathbb{F}_i$$

$$= \mathbb{J}_\alpha \cdot \vec{\nabla} \left(\frac{1}{T} \right) + \mathbb{J}_P^{\alpha\beta} \Big|_{NSO} \left(-\frac{1}{T} \frac{\partial v_\alpha}{\partial x^\beta} \right)$$

$$= -\kappa (\vec{\nabla} T) \cdot \vec{\nabla} \left(\frac{1}{T} \right) + (\pi^{\alpha\beta} - P \delta^{\alpha\beta}) \left(-\frac{1}{T} \frac{\partial v_\alpha}{\partial x^\beta} \right)$$

$$= \kappa T^2 \left(\vec{\nabla} \left(\frac{1}{T} \right) \right)^2 - \frac{1}{T} \left(\frac{\partial v_\alpha}{\partial x^\beta} \right) \left(-2\eta \sigma^{\alpha\beta} - \rho (\vec{\nabla} \cdot \vec{v}) \delta^{\alpha\beta} \right)$$

$$= \kappa T^2 \left(\vec{\nabla} \left(\frac{1}{T} \right) \right)^2 + \frac{\rho}{T} (\vec{\nabla} \cdot \vec{v})^2 + \frac{2\eta}{T} \sum_{\alpha\beta} (\sigma^{\alpha\beta})^2$$

$$\geq 0 \quad \text{for } \kappa, \rho, \eta \geq 0$$

where

$$2\eta \sigma^{\alpha\beta} \frac{\partial v^\alpha}{\partial x^\beta} = 2\eta \sigma^{\alpha\beta} \left(\frac{1}{2} \left(\frac{\partial v^\alpha}{\partial x^\beta} + \frac{\partial v^\beta}{\partial x^\alpha} \right) - \frac{1}{3} (\vec{\nabla} \cdot \vec{v}) \delta^{\alpha\beta} \right)$$

can add due
to $\sigma^{\alpha\beta} = \sigma^{\beta\alpha}$

can add due
to $\sigma^{\alpha\beta} \sigma^{\alpha\beta} = \text{tr}[\sigma^2]$

Can now look at dissipation of kinetic energy in incompressible fluid

$$\frac{d}{dt} E_{kin} = \rho \int d^3r \quad v_\alpha \left(\frac{d}{dt} v_\alpha \right)$$

$$\stackrel{NS eqn}{=} \int d^3r \quad v_\alpha \left(-\rho \left(v_\beta \frac{\partial}{\partial x_\beta} \right) v_\alpha - \frac{\partial}{\partial x_\alpha} P + \eta \frac{\partial^2}{\partial x_\beta \partial x_\beta} v_\alpha \right)$$

now can rewrite

$$A) \quad v_\alpha \frac{\partial}{\partial x_\alpha} P = \frac{\partial}{\partial x_\alpha} (v_\alpha P) - P \left(\frac{\partial}{\partial x_\alpha} v_\alpha \right)$$

$$B) \quad v_\alpha \rho v_\beta \frac{\partial}{\partial x_\beta} v_\alpha = \cancel{\rho v_\beta} \frac{\partial}{\partial x_\beta} \left(\frac{1}{2} v^2 \right) \\ = \frac{\partial}{\partial x_\beta} \left(v_\beta \frac{1}{2} \rho v^2 \right) - \frac{1}{2} \rho v^2 \left(\frac{\partial}{\partial x_\beta} v_\beta \right)$$

$$C) \quad v_\alpha \eta \frac{\partial^2}{\partial x_\beta \partial x_\beta} v_\alpha = \frac{\partial}{\partial x_\beta} \left(v_\alpha \frac{\partial}{\partial x_\beta} v_\alpha \right) - \eta \left(\frac{\partial v_\alpha}{\partial x_\beta} \right) \left(\frac{\partial v_\alpha}{\partial x_\beta} \right)$$

note that we assumed $\eta = \text{const}$ in NS eqns

so

$$\frac{d}{dt} E_{kin} = \int d^3r \quad \frac{\partial}{\partial x_\alpha} \left(-v_\alpha \left(P + \frac{1}{2} \rho v^2 \right) + \frac{1}{2} \eta \frac{\partial v^2}{\partial x_\alpha} \right) - \eta \int d^3r \quad \left(\frac{\partial v_\alpha}{\partial x_\beta} \right) \left(\frac{\partial v_\alpha}{\partial x_\beta} \right)$$

Since the first term is a surface contribution
which vanishes if $v \rightarrow 0$ for $|\vec{r}| \rightarrow \infty$
one is left with

$$\frac{d}{dt} E_{\text{kin}} = -\eta \int d^3r \left(\frac{\partial v_x}{\partial x_b} \right) \left(\frac{\partial v_x}{\partial x_b} \right) \leq 0$$

\Rightarrow Kinetic energy is dissipated into
internal energy of the fluid
due to viscous effects

Besides dynamized problems one important application
of fluid dynamics is to study ~~stationary~~ stationary states
Hydrostatic:

$$\frac{\partial}{\partial t} = 0, \quad \vec{v} = 0$$

Need to consider external forces as well

$$\vec{\nabla} p = \vec{F}_{\text{ext}}$$

as gravity $\vec{F}_{\text{ext}} = -\rho \vec{e}_z$

$$\Rightarrow \frac{\partial p}{\partial z} = -\rho$$

ideal gas $pV = Nk_B T$

$$p = \frac{Nk_B T}{V} = \rho \frac{k_B T}{m}$$

$$\Rightarrow \frac{\partial}{\partial z} p = - \frac{mg}{k_B T} p$$

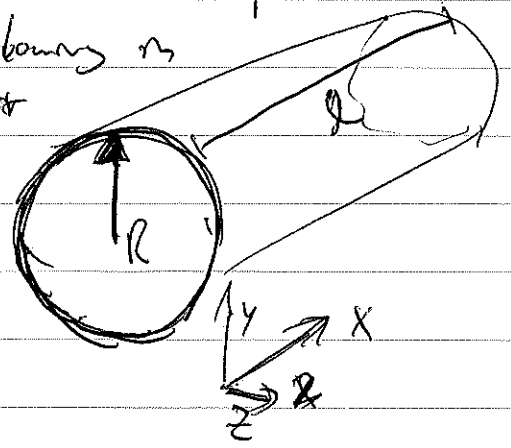
$$p = p_0 e^{-\frac{mgz}{k_B T}}$$

Steady flow in a pipe:

~~$\vec{v} = v_x \vec{e}_x$~~
 $\vec{v} = v_x \vec{e}_x$

Incompressible

We consider incompressible fluid flowing in cylinder



$$\frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot (\rho \vec{v}) = 0$$

So for $\rho = \text{const}$ $\vec{\nabla} \cdot \vec{v} = 0 \Rightarrow \frac{\partial}{\partial x} v_x = 0$

$$\vec{v} = v_x(r) \vec{e}_x$$

where φ depends on r by azimuthal symmetry

Now let's look at NS equation

$$\rho \left[\frac{\partial \vec{v}}{\partial t} + (\vec{v} \cdot \vec{\nabla}) \vec{v} \right] = -\vec{\nabla} p + \rho \vec{\nabla} \cdot (\vec{\nabla} \cdot \vec{v}) + \eta \left(\Delta \vec{v} + \frac{1}{3} \vec{\nabla} (\vec{\nabla} \cdot \vec{v}) \right)$$

Since fluid is incompressible ($\vec{\nabla} \cdot \vec{v} = 0$) and flow is stationary ($\frac{\partial \vec{v}}{\partial t} = 0$)

$$\Rightarrow \eta \Delta v_x = \frac{dp}{dx}$$

assuming const viscosity we get

$$\eta \Delta \left[\frac{\partial}{\partial x} v_x \right] = \frac{dp}{dx} \Rightarrow \frac{dp}{dx} = \text{const}$$

So we conclude that

$$\frac{dp}{dx} = \frac{p_{out} - p_{in}}{l} = -\frac{\Delta p}{l}$$

where the pressure drops from in to out
 $\Delta p > 0$

$$\eta \Delta V_x = -\frac{\Delta p}{l} \quad \text{where } \eta \text{ is cylinder coordinate} \quad \Delta = \frac{1}{r} \frac{d}{dr} \left(r \frac{d}{dr} \right)$$

$$\Rightarrow \frac{1}{r} \frac{d}{dr} \left(r \frac{dV_x}{dr} \right) = -\frac{\Delta p}{\eta l}$$

So we obtain
the general
solution

$$r \frac{dV_x}{dr} = -\frac{k}{2} \frac{\Delta p}{\eta l} r^2 + a$$

$$V_x(r) = -\frac{1}{4} \frac{\Delta p}{\eta l} r^2 + a \log(r) + b$$

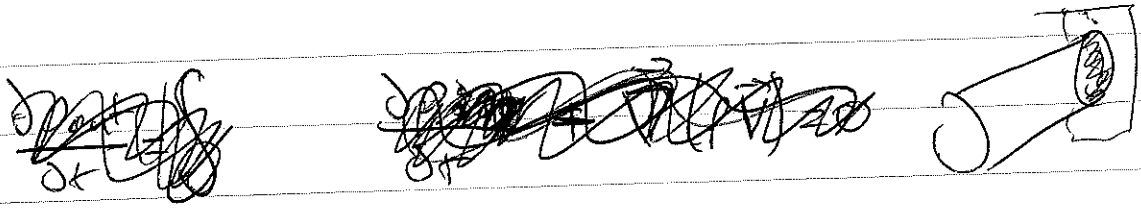
How to fix coefficients a, b ?

1) Boundary conditions require $V_x(R) = 0$
at walls of cylinder

2) Flow velocity should be finite in
center ($\lim_{r \rightarrow 0} \log(r) = -\infty \Rightarrow a = 0$)

$$V_x(r) = \frac{1}{4} \frac{\Delta p}{\eta l} (R^2 - r^2)$$

Can also calculate mass flux through pipe



$$Q = \int d\vec{\sigma} \cdot \rho \vec{v}$$

"disc charge"

$$= 2\pi r \rho \int dr r v_x(r)$$

$$= \frac{\pi \Delta p}{8\eta l} R^4 \rho$$

Bigger pipes transport more ($\propto R^4$)

a) because they are bigger

b) because the slow flow near the wall has a smaller impact on the bottom in the center