

Recap:

## Calculation of transport coefficients

Discussion in Maro dealt the case of electron conduction and current motion in previous discussion.

By considering balance equation for momentum for multi-carrier point systems

$$\sum_i \langle m_i n_i \vec{v}_i \rangle = \sum_i q_i n_i \vec{E}$$

System is subject to constant acceleration unless it is electrically neutral

$$\sum_i q_i n_i = 0$$

Can search for stationary solutions for electrically neutral system

→ calculation of transport coefficients applies as discussed

Developed a picture of collisions where positive & negative charge carriers are accelerated in different directions due to  $\vec{E}$  field

Interactions between different particles  
Scattering, induces a damping force on electrons

e.g. Drude model

$$m_i \frac{d\langle \vec{v} \rangle}{dt} + m_i \frac{\langle \vec{v} \rangle}{\tau} = q_i \vec{E}$$

Simplest realization is in terms of Lorentz gas

# Calculation of diffusion coefficient & heat conductance

We again consider two component system

e.g. Lorentz gas (interaction with other scattering centers)

microscopically model particles  
in gas

Basic strategy same as usual

- Consider limit of Maxwell & Boltzmann (local approx)

- Search for local equilibrium  
solution  $f^{(0)}$

(in this case with gradients in  $T, \mu$ )

- Construct near equilibrium expansion  $f^{(1)}$   
according to first order of Hilbert expansion

$$\left( \frac{\partial}{\partial t} + \vec{p} \cdot \vec{\nabla}_r + \vec{F} \cdot \frac{\partial}{\partial \vec{p}} \right) f^{(1)} = - \mathcal{L} f^{(1)}$$

- Invert collision operator (e.g. via RTA)

- Calculate currents

$$\vec{J}_N = \int \vec{p} \frac{\vec{p}}{m} f$$

$$\vec{J}_E = \int \vec{p} \frac{\vec{p}^2}{2m} f$$

- read off coefficient  $D$  in expansion of equilibrium  
relations in affinities

$$\text{e.g. } \vec{J}_N = \underbrace{L_{NN}} \vec{v} \left( -\frac{\mu}{T} \right) + \underbrace{L_{NE}} \vec{v} \left( \frac{1}{T} \right)$$

Microscopically calculated coefficient automatically  
satisfy Onsager relations (Casimir-Onsager principle)

# Hydrodynamics from Boltzmann equation

We have seen that the Boltzmann equation can describe relaxation of a non-equilibrium system towards global equilibrium based on microscopic description in terms of single particle phase space density

Eventually we expect that in the long time limit, evolution should become "simpler", i.e. it can be described by local thermodynamic variables as in Chapter 1

Computation:

$$\text{BTE} = f(\vec{r}, \vec{p}) \left( \frac{\partial}{\partial t} + \vec{v} \cdot \nabla_{\vec{r}} + \vec{F} \cdot \nabla_{\vec{p}} \right) = -C[f]$$

Hydro: conservation laws for  $e, n, \vec{p}$

$$\frac{\partial n}{\partial t} + \vec{\nabla} \cdot \vec{J}_n = 0$$

constitutive relations

$$\vec{J}_n = \vec{J}_n^0 + \frac{1}{n\alpha} \vec{F} \alpha$$

equation of state

$$n = n(T, \mu, \vec{v})$$

Clearly hydrodynamic description involves fewer dof's

Goal is to understand how reduction to small number of dof's is possible

We are interested in evolution of expectation values of one body operators, according to

$$\langle x(t; \vec{r}, \vec{p}) \rangle_{\vec{p}} = \frac{1}{n(t; \vec{r})} \int_{\vec{p}} x(t; \vec{r}, \vec{p}) f(t; \vec{r}, \vec{p})$$

and we know how to derive EOMs for such quantities from the Boltzmann equation

Specifically if  $x(t; \vec{r}, \vec{p})$  is a collision invariant, we know that contributions from collision integral vanish

$$\begin{aligned} \frac{d}{dt} n \langle x \rangle_{\vec{p}} - n \left\langle \frac{\partial x}{\partial t} \right\rangle_{\vec{p}} + n \int_{\vec{p}} x \vec{p}_m \vec{\nabla}_r \\ + n \int_{\vec{p}} x \vec{F} \vec{\nabla}_p f = n \langle x C[f] \rangle_{\vec{p}} = 0 \end{aligned}$$

So upon integration by parts

$$\begin{aligned} \frac{d}{dt} n \langle x \rangle_{\vec{p}} - n \left\langle \frac{\partial x}{\partial t} \right\rangle_{\vec{p}} + \vec{\nabla}_r \langle n x \vec{p}_m \rangle_{\vec{p}} - n \left\langle \frac{\vec{p}_m}{m} \vec{\nabla}_r x \right\rangle_{\vec{p}} \\ - n \vec{F} \langle \vec{\nabla}_p x \rangle_{\vec{p}} = 0 \end{aligned}$$

Can now find equivalent form of balance equations convenient for derivation of fluid dynamic equations

choosing  $\chi = m$        $\vec{\nabla}_r \chi = 0$        $\vec{\nabla}_p \chi = 0$        $\frac{d}{dt} \chi = 0$

$$\frac{d}{dt} \rho(t, \vec{r}) + \vec{\nabla}_r \left( \rho(t, \vec{r}) \langle \frac{\vec{p}}{m} \rangle_p \right) = 0$$

Defining  $\vec{V}(t, \vec{r}) = \langle \frac{\vec{p}}{m} \rangle_p$  we get the usual continuity eqn

$$\left( \frac{d}{dt} \rho(t, \vec{r}) + \vec{\nabla}_r \left( \rho(t, \vec{r}) \vec{V}(t, \vec{r}) \right) \right) = 0$$

Next we consider the kinetic momentum

$$\chi^i = p^i \quad \vec{\nabla}_r \chi^i = 0 \quad \vec{\nabla}_p \chi^i = \delta^{ij} \quad \frac{d}{dt} \chi = 0$$

$$\frac{d}{dt} \rho(t, \vec{r}) v^i(t, \vec{r}) + \vec{\nabla}_p \left\langle \rho(t, \vec{r}) \frac{p^i}{m} \frac{\vec{p}}{m} \right\rangle_p = \frac{\Delta(t, \vec{r})}{m} \vec{F}^i(t, \vec{r})$$

where we encounter  $\langle \frac{p^i}{m} \frac{\vec{p}}{m} \rangle_p$  as a new object. If the system features a non-zero velocity  $\vec{V}(t, \vec{r})$  it makes sense to separate avg. values from result in local rest frame (lrf)

$$\left\langle \frac{\vec{p}}{m} \frac{\vec{p}}{m} \right\rangle_p = \left\langle \left( \frac{\vec{p}}{m} - \vec{V}_i(t, \vec{r}) \right) \left( \frac{\vec{p}}{m} - \vec{V}_j(t, \vec{r}) \right) \right\rangle_p + \vec{V}_i(t, \vec{r}) \vec{V}_j(t, \vec{r})$$

Since the first term survives in lrf we can then identify

$$\Pi_{ij}(t, \vec{r}) = \rho(t, \vec{r}) \left\langle \left( \frac{p_i}{m} - v_i \right) \left( \frac{p_j}{m} - v_j \right) \right\rangle_p$$

~~stress~~ stress tensor

So we are left with the form

$$n \left\langle \frac{p_i^s}{m} \frac{dv_i^s}{dt} (p^s - m v^s) \right\rangle_p$$
$$= \underbrace{\frac{m n}{\rho}}_{\equiv \Pi^s} \left[ \left\langle \frac{p_i^s p_i^s}{m m} \right\rangle - \underbrace{\left\langle \frac{v_i^s p_i^s}{v^s v^s} \right\rangle} \right] \frac{dv_i^s}{dt}$$

$$= \Pi^s \frac{dv_i^s}{dt}$$

So collecting everything we find the balance equation

$$\left[ \frac{\partial e(t, \vec{r})}{\partial t} + \vec{\nabla} \cdot \left( \vec{J}_e(t, \vec{r}) + e(t, \vec{r}) \vec{v}(t, \vec{r}) \right) + \Pi^s \frac{dv_i^s}{dt}(t, \vec{r}) \right] = 0$$

for the internal energy

we thus get the balance equation

$$\left( \frac{\partial}{\partial t} \rho(t, \vec{r}) v^i(t, \vec{r}) + \frac{\partial}{\partial x_j} \left[ \rho(t, \vec{r}) v^j(t, \vec{r}) v^i(t, \vec{r}) + \Pi^{ij}(t, \vec{r}) \right] = \frac{1}{m} \rho(t, \vec{r}) F^i(t, \vec{r}) \right)$$

So far nothing really new but now let us consider energy. What we really care about is internal energy  $e$  related to motion of gas particles in LRF, since change in velocity already described by momentum balance

$$\chi(t, \vec{r}, \vec{p}) = \frac{(\vec{p} - m\vec{v}(t, \vec{r}))^2}{2m}$$

$$\frac{\partial}{\partial t} \chi = - \frac{\partial \vec{v}}{\partial t} \cdot (\vec{p} - m\vec{v}(t, \vec{r}))$$

$$\vec{\nabla}_j \chi = - \vec{\nabla}_j \vec{v} \cdot (\vec{p} - m\vec{v}(t, \vec{r}))$$

$$\vec{\nabla}_p \chi = \left( \frac{\vec{p}}{m} - \vec{v}(t, \vec{r}) \right)$$

Define  $e(t, \vec{r}) = \frac{1}{2} \rho(t, \vec{r}) \left\langle \left( \frac{\vec{p}}{m} - \vec{v}(t, \vec{r}) \right)^2 \right\rangle_{\vec{p}} = n \langle \chi \rangle_{\vec{p}}$

$$\begin{aligned} \frac{\partial}{\partial t} e(t, \vec{r}) + \rho \frac{\partial \vec{v}}{\partial t} \cdot \underbrace{\left\langle \frac{\vec{p}}{m} - \vec{v} \right\rangle_{\vec{p}}}_{=0} + \vec{\nabla}_R \cdot \left\langle n \frac{(\vec{p} - m\vec{v})^2}{2m} \frac{\vec{p}}{m} \right\rangle_{\vec{p}} \\ + n \left\langle \frac{\rho_0}{m} \frac{\partial v^i}{\partial t} (\vec{p} - m\vec{v}^i) \right\rangle_{\vec{p}} \\ + n \vec{v} \cdot \underbrace{\left\langle \frac{\vec{p}}{m} - \vec{v} \right\rangle_{\vec{p}}}_{=0} = 0 \end{aligned}$$

we recognize that

$$\left\langle n \frac{(\vec{p} - m\vec{v})^2}{2m} \frac{\vec{p}}{m} \right\rangle_{\vec{p}} = \underbrace{\left\langle n \frac{(\vec{p} - m\vec{v})^2}{2m} \left( \frac{\vec{p}}{m} - \vec{v} \right) \right\rangle}_{\text{energy flux in LRF}} + n \vec{v} \cdot \vec{e}_3$$

$$\vec{J}_u = \left\langle n \frac{(\vec{p} - m\vec{v})^2}{2m} \left( \frac{\vec{p}}{m} - \vec{v} \right) \right\rangle_{\vec{p}} = \frac{1}{2} \rho \left\langle \left( \frac{\vec{p}}{m} - \vec{v} \right)^2 \left( \frac{\vec{p}}{m} - \vec{v} \right) \right\rangle_{\vec{p}}$$

Now this concludes part 1) of the derivation  
of hydrodynamics, what remains to do soon  
is how constitutive relations emerge from  
Boltzmann framework

Generally this will result in reduction  
of dof's to local thermodynamic properties  
and their gradients

→ necessary to truncate Boltzmann  
equation

Note that different truncations are possible  
corresponding to different expansion schemes/  
power countings

→ active topic of research in particular  
for relativistic theories

We will discuss traditional way  
based on Chapman-Enskog expansion

which can be viewed as a strict  
expansion in Knudsen number